

**GUJARAT TECHNOLOGICAL UNIVERSITY****BE - SEMESTER-VI (NEW) EXAMINATION – SUMMER 2022****Subject Code:3160104****Date:03/06/2022****Subject Name:Basic control theory****Time:10:30 AM TO 01:00 PM****Total Marks: 70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Simple and non-programmable scientific calculators are allowed.

**MARKS**

<b>Q.1</b>	(a)	Explain the difference between open and closed loop control system	<b>03</b>
	(b)	Guided missile control is an example of the closed loop control system. Justify the statement.	<b>04</b>
	(c)	Explain the steps for block diagram reduction method	<b>07</b>
<b>Q.2</b>	(a)	Explain the mason's gain formulae	<b>03</b>
	(b)	Explain the SFG with one example in detail	<b>04</b>
	(c)	Explain Time domain specification in detail	<b>07</b>
<b>OR</b>			
	(c)	Explain the steps for plotting the root locus	<b>07</b>
<b>Q.3</b>	(a)	Explain Routh's criteria.	<b>03</b>
	(b)	Derive the transfer function for RLC series circuit	<b>04</b>
	(c)	Explain steady state error for Type-0, 1 and 2 system.	<b>07</b>
<b>OR</b>			
<b>Q.3</b>	(a)	Explain various types of standard test input signals	<b>03</b>
	(b)	Explain the difference between the modern control system and conventional control system	<b>04</b>
	(c)	Explain steps for designing the Bode plot	<b>07</b>
<b>Q.4</b>	(a)	Explain difference between natural and manmade control system	<b>03</b>
	(b)	Explain spring, mass and damper system in detail	<b>04</b>
	(c)	Derive the steps for designing the Nyquist plot	<b>07</b>
<b>OR</b>			
<b>Q.4</b>	(a)	Explain ON-OFF controller with dead zone	<b>03</b>
	(b)	Explain the function of proportional controller	<b>04</b>
	(c)	Explain PID controller	<b>07</b>
<b>Q.5</b>	(a)	Explain Nyquist stability criteria	<b>03</b>
	(b)	Explain linear time invariant systems	<b>04</b>
	(c)	Explain desired features of feedback control algorithms	<b>07</b>
<b>OR</b>			
<b>Q.5</b>	(a)	Explain Hurwitz criteria	<b>03</b>
	(b)	Explain the difference between SISO and MIMO system	<b>04</b>
	(c)	Explain the state space representation in detail and its importance in control theory	<b>07</b>

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