

**GUJARAT TECHNOLOGICAL UNIVERSITY**

**BE - SEMESTER-VI EXAMINATION – SUMMER 2025**

**Subject Code: 3161009**

**Date: 30-05-2025**

**Subject Name: Embedded Systems**

**Time: 10:30 AM TO 01:00 PM**

**Total Marks:70**

**Instructions:**

1. **Attempt all questions.**
2. **Make suitable assumptions wherever necessary.**
3. **Figures to the right indicate full marks.**
4. **Simple and non-programmable scientific calculators are allowed.**

- Q.1** (a) Write down skills Required for an Embedded System Designer. **03**  
(b) What is and Embedded system? What are its characteristics? **04**  
(c) Explain the working of the Secure Digital Input Output (SDIO) protocol. **07**
- Q.2** (a) What is watch dog Timer? Explain its function in brief. **03**  
(b) How does Brown Out Reset work in microcontroller? **04**  
(c) Explain the working of Spy-Bi-Wire serial communication protocol. **07**
- OR**
- (c) List down wireless communication protocol and explain any one in detail. **07**
- Q.3** (a) Describe Earliest Deadline First Mechanism with example. **03**  
(b) Explain concept of interrupt service routine. **04**  
(c) What is context switching? Explain context switching on interrupts. **07**
- OR**
- Q.3** (a) Describe MSP430 USCI module and its modes. **03**  
(b) What do you mean by Mutex? Also explain P and V semaphore with appropriate example. **04**  
(c) Describe the main problem with semaphores and its limitation. **07**
- Q.4** (a) Describe the four sources of clock in MSP430 processor. **03**  
(b) MSP430 is having an orthogonal CPU architecture supported with RISC features. – Justify the statement. **04**  
(c) What is inter process communication (IPC)? List down and explain methods of IPC in brief. **07**
- OR**
- Q.4** (a) Explain the special features associated with GPIO port pins in MSP430 other than simple digital input output port pin characteristics. **03**  
(b) Sketch diagram to interface DMA with microprocessor or microcontroller **04**  
(c) Give difference between Multiprocessing and Multithreading. **07**
- Q.5** (a) List down features of an operating system. **03**  
(b) What is meant by benchmarking Real time operating system (RTOS)? Why it is required? **04**  
(c) Draw interfacing diagram to interface 8 LEDs with MSP430. Turn-ON LEDs in ring counter fashion. **07**
- OR**
- Q.5** (a) Describe Round Robin with Interrupts. **03**  
(b) Explain Rate-monotonic scheduling. **04**  
(c) Differentiate between Clock-driven and Event-driven Scheduling. **07**

**GUJARAT TECHNOLOGICAL UNIVERSITY**

**BE - SEMESTER-VI (NEW) EXAMINATION – SUMMER 2024**

**Subject Code:3161009**

**Date:24-05-2024**

**Subject Name:Embedded Systems**

**Time:10:30 AM TO 01:00 PM**

**Total Marks:70**

**Instructions:**

1. **Attempt all questions.**
2. **Make suitable assumptions wherever necessary.**
3. **Figures to the right indicate full marks.**
4. **Simple and non-programmable scientific calculators are allowed.**

- Q.1** (a) Give classification of Embedded systems. **03**  
(b) What is mean by embedded systems? What are the components of it? Give examples of embedded system. **04**  
(c) Explain USB Protocol in detail. **07**
- Q.2** (a) List the down features of Bluetooth protocol. **03**  
(b) What is inter process communication? How it is done? **04**  
(c) Compare: IrDA, Wi-Fi and ZigBee. **07**
- OR**
- (c) Explain following: **07**  
1. Context and the Periods for Context Switching,  
2. Interrupt Latency and Deadline
- Q.3** (a) List down the steps executed before handling an Interrupt in an embedded system. **03**  
(b) Describe the information required for writing a device driver. **04**  
(c) What is Semaphore? Write down advantages and disadvantages of semaphore. **07**
- OR**
- Q.3** (a) List down the services provided by RTOS. **03**  
(b) Explain Earliest-Deadline First Scheduling. **04**  
(c) Write down various types of states of tasks? Explain them. **07**
- Q.4** (a) Write down the features of an operating system. **03**  
(b) Give comparison between process and thread. **04**  
(c) What is multitasking? Differentiate between Preemptive and Cooperative Multitasking. **07**
- OR**
- Q.4** (a) Discuss watch dog timer of MSP430. **03**  
(b) Write down advantages and disadvantages of RTOS. **04**  
(c) Describe Round-robin with interrupt mechanism for embedded software. **07**
- Q.5** (a) Describe low power mode of MSP430. **03**  
(b) Describe the various sources of clock in MSP430 processor. **04**  
(c) List down various registers of MSP430 processor with their functions. **07**
- OR**
- Q.5** (a) Explain: 1.RPC function 2.Socket function. **03**  
(b) Differentiate Clock driven and Event driven scheduling. **04**  
(c) Explain how the timers of MSP430 can be configured for PWM generation. **07**

\*\*\*\*\*

**GUJARAT TECHNOLOGICAL UNIVERSITY****BE - SEMESTER-VI (NEW) EXAMINATION – SUMMER 2023****Subject Code:3161009****Date:14-07-2023****Subject Name:Embedded Systems****Time:10:30 AM TO 01:00 PM****Total Marks:70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Simple and non-programmable scientific calculators are allowed.

**MARKS**

- |            |   |           |
|------------|---|-----------|
| <b>Q.1</b> | <b>(a)</b> Write down the skills required for an Embedded System Designer.  | <b>03</b> |
|            | <b>(b)</b> Describe an embedded processor as (i) GPP (ii) ASIP (iii) Single purpose processor.  | <b>04</b> |
|            | <b>(c)</b> Differentiate between serial and parallel communication. Explain USART protocol in brief.  | <b>07</b> |
| <b>Q.2</b> | <b>(a)</b> Describe the features associated with Bluetooth and Zigbee protocols used in wireless and mobile systems.  | <b>03</b> |
|            | <b>(b)</b> List the features associated with AHB and ASB Buses.   | <b>04</b> |
|            | <b>(c)</b> Explain I2C and CAN bus protocol in brief.   | <b>07</b> |
|            | <b>OR</b>   |           |
|            | <b>(c)</b> What is Device driver? Explain role of Interrupt in Device driver programming.   | <b>07</b> |
| <b>Q.3</b> | <b>(a)</b> Explain different types of interrupt sources.  | <b>03</b> |
|            | <b>(b)</b> What is Semaphore? Explain where Semaphore can be utilized?  | <b>04</b> |
|            | <b>(c)</b> Give advantages, disadvantages and uses of mailbox, pipe and socket functions in interprocess communication.   | <b>07</b> |
|            | <b>OR</b>   |           |
| <b>Q.3</b> | <b>(a)</b> Explain the differences between Preemptive & Non-Preemptive scheduling policies.   | <b>03</b> |
|            | <b>(b)</b> Define Interrupt Latency and Interrupt Service Deadline. Describe the parameters that govern their values  | <b>04</b> |
|            | <b>(c)</b> Explain device, file and I/O management in RTOS.   | <b>07</b> |
| <b>Q.4</b> | <b>(a)</b> What is RTOS ? Describe types of RTOS with two examples.   | <b>03</b> |
|            | <b>(b)</b> Define and explain different Benchmarking parameters for an RTOS.  | <b>04</b> |
|            | <b>(c)</b> Explain process context switching and thread context switching in detail. Justify “threads are lightweight processes”.                               | <b>07</b> |
|            | <b>OR</b>   |           |
| <b>Q.4</b> | <b>(a)</b> Define: Process Control Block. Which data is stored in PCB?  | <b>03</b> |
|            | <b>(b)</b> Describe the differences between Hard Real Time and Soft Real Time System with an example of each one.   | <b>04</b> |
|            | <b>(c)</b> Compare process, task and thread with an appropriate example. Explain multithreading mechanism in context of the display process of desktop systems. | <b>07</b> |
| <b>Q.5</b> | <b>(a)</b> Explain the function of Watchdog timer in MSP430 processor.  | <b>03</b> |
|            | <b>(b)</b> Describe the four sources of clock in MSP430 processor   | <b>04</b> |
|            | <b>(c)</b> Explain interrupt handling process in MSP430.  | <b>07</b> |
|            | <b>OR</b>   |           |
| <b>Q.5</b> | <b>(a)</b> Describe POR, PUC and BOR for MSP430.  | <b>03</b> |
|            | <b>(b)</b> MSP430 is having an orthogonal CPU architecture supported with RISC features. – Justify the statement.   | <b>04</b> |
|            | <b>(c)</b> Explain the use of timer for generating Pulse Width Modulated waveform using MSP430.   | <b>07</b> |

**GUJARAT TECHNOLOGICAL UNIVERSITY****BE - SEMESTER-VI (NEW) EXAMINATION – SUMMER 2022****Subject Code:3161009****Date:10/06/2022****Subject Name:Embedded Systems****Time:10:30 AM TO 01:00 PM****Total Marks: 70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Simple and non-programmable scientific calculators are allowed.

		<b>MARKS</b>
<b>Q.1</b>	(a) Define and classify the embedded systems, give few examples of such systems.	<b>03</b>
	(b) Describe skills required for embedded design engineer.	<b>04</b>
	(c) Describe Direct Memory Access.	<b>07</b>
<b>Q.2</b>	(a) Define RTOS. Enlist types of RTOS with examples.	<b>03</b>
	(b) Describe Watch Dog Timer and Brown Out Reset with example.	<b>04</b>
	(c) Compare Wi-Fi, Blue-tooth and Zigbee algorithm	<b>07</b>
	<b>OR</b>	
	(c) Compare the advantages and disadvantages of data transfers using serial and parallel ports devices. Describe SPI protocol.	<b>07</b>
<b>Q.3</b>	(a) Describe busy wait approach for accessing IO.	<b>03</b>
	(b) Differentiate : Process and Thread	<b>04</b>
	(c) Describe shared data problem with example. How to solve this issue?	<b>07</b>
	<b>OR</b>	
<b>Q.3</b>	(a) Describe interrupt mechanism for accessing IO.	<b>03</b>
	(b) Describe Mailbox function for IPC.	<b>04</b>
	(c) Describe Priority inversion and Deadlock condition. How to solve these issues?	<b>07</b>
<b>Q.4</b>	(a) Describe Earliest Deadline First Mechanism with example.	<b>03</b>
	(b) Differentiate : Binary Semaphore and Mutex	<b>04</b>
	(c) Describe Round-robin with interrupt mechanism for embedded software.	<b>07</b>
	<b>OR</b>	
<b>Q.4</b>	(a) Define : Process Control Block. Which data is stored in PCB?	<b>03</b>
	(b) Describe Critical Section. How to achieve this functionality in programming.	<b>04</b>
	(c) Describe co-operative and pre-emptive scheduling mechanism.	<b>07</b>
<b>Q.5</b>	(a) Sketch and Describe block diagram of MSP430	<b>03</b>
	(b) Describe low-power modes of MSP430.	<b>04</b>
	(c) Common cathode seven-segment and push-button is connected with MSP430. Sketch interfacing diagram and write C-code to count number of times switch is pressed (Use interrupt subroutine when switch is connected)	<b>07</b>

**OR**

- Q.5** (a) Describe multiplexing scheme in MSP430 processor for the port pins. **03**  
(b) Describe clocking system of MSP430. **04**  
(c) Describe MSP430 timer modes available for Timer-A. Write C-Program for MSP430 to generate 1KHz square wave on pin P1.0 using Timer-A. **07**

\*\*\*\*\*