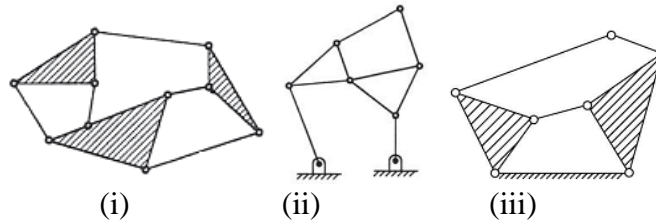
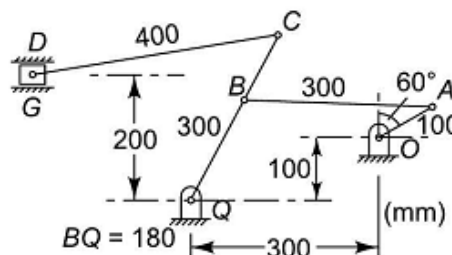


**GUJARAT TECHNOLOGICAL UNIVERSITY****BE - SEMESTER-III EXAMINATION – SUMMER 2025****Subject Code:3131906****Date:06-06-2025****Subject Name:Kinematics and Theory of Machines****Time:02:30 PM TO 05:00 PM****Total Marks:70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Simple and non-programmable scientific calculators are allowed.

**MARKS****Q.1 (a)** Find the degrees of freedom for the given configurations.**03****(b)** How are the kinematic pairs classified? Explain with examples.**04****(c)** Explain the inversions of the single slider crank mechanism.**07****Q.2 (a)** Define Type, Number and Dimensional synthesis.**03****(b)** In a crank and slotted lever mechanism, the length of crank is 560 mm and the ratio of time of working stroke to return stroke is 2.8. Determine (a) distance between the fixed centres, and (b) the length of the slotted lever, if length of stroke is 250 mm.**04****(c)** A four bar mechanism is to be synthesized by using three precision points from Chebyshev's spacing to generate the function  $y = x^2$ , for the range  $0 \leq x \leq 1$ . Input link is to start from  $30^\circ$  and  $\Delta\theta = 90^\circ$ . The output link is to start at  $30^\circ$  and  $\Delta\phi = 90^\circ$ . Find out the values of corresponding  $\theta$  and  $\phi$ .**07****OR****(c)** Design a slider crank mechanism to coordinate three positions of the input and of the slider for the following data by inversion method. Eccentricity = 20 mm.  $\theta_{12} = 30^\circ$ ,  $\theta_{13} = 60^\circ$ ,  $S_{12} = 40$  mm,  $S_{13} = 96$  mm.**07****Q.3 (a)** In the mechanism shown in figure the crank OA rotates at 210 rpm clockwise. For the given configuration, determine (i) velocity and acceleration of slider D, (ii) angular velocity and angular acceleration of the link CD.**14****OR****Q.3 (a)** Explain the types of I- Centres. What is the use of Kennedy's theorem?**04****(b)** Figure shows a six link mechanism. The dimensions of the links are OA = 100 mm, AB = 450 mm, BD = 200 mm, QB = 400 mm, DE = 200 mm,**10**

- OR**

- Q.5**
- |     |   |           |
|-----|---|-----------|
| (a) | What are various kinds of friction? Discuss each in brief.  | <b>03</b> |
| (b) | A differential band brake has a drum with a diameter of 800 mm. The two ends of the band are fixed to the pins on the opposite sides of the fulcrum of the lever at distances of 40 mm and 200 mm from the fulcrum. The angle of contact is $270^\circ$ and the $\mu = 0.2$ . Determine the brake torque when a force of 600 N is applied to the lever at a distance of 800 mm from the fulcrum. Consider clockwise rotation of the drum. | <b>04</b> |
| (c) | Two $20^\circ$ involute spur gears mesh externally and give a velocity ratio of 3. The module is 3 mm and the addendum is equal to 1.1 module. If the pinion rotates at 120 rpm, determine the (i) minimum number of teeth on each wheel to avoid interference, (ii) contact ratio.   | <b>07</b> |

OR

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