

Enrollment No./Seat No.:

**GUJARAT TECHNOLOGICAL UNIVERSITY**  
**Bachelor of Engineering - SEMESTER - III EXAMINATION - SUMMER 2025**

**Subject Code: 3131101**

**Date: 29-05-2025**

**Subject Name: Control Systems**

**Time: 02:30 PM TO 05:00 PM**

**Total Marks: 70**

**Instructions**

- 1. Attempt all questions.**
- 2. Make suitable assumptions wherever necessary.**
- 3. Figures to the right indicate full marks.**

	<b>Marks</b>
<b>Q.1 (a)</b> Define i) Settling time ii) Peak time iii) Peak Overshoot	<b>03</b>
<b>(b)</b> Explain Force Voltage analogy.	<b>04</b>
<b>(c)</b> Derive the expression of a second order control system subjected to unit step signal.	<b>07</b>
<b>Q.2 (a)</b> State advantages and limitations of Routh stability criterion.	<b>03</b>
<b>(b)</b> Explain the steps of Bode plot.	<b>04</b>
<b>(c)</b> State root locus technique rules.	<b>07</b>

**OR**

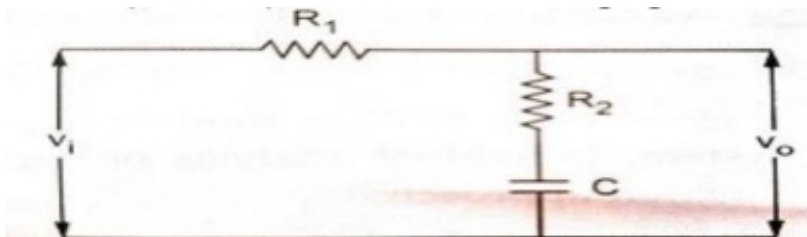
- |   |           |
|---|-----------|
| <b>(c)</b> Sketch the complete root locus of system having unity feedback and | <b>07</b> |
|---|-----------|

$$G(S) = \frac{K}{S(S+2)(S+4)}$$

<b>Q.3 (a)</b> Explain standard test signals.	<b>03</b>
<b>(b)</b> Find laplace transform of $x(t) = \cosh(4t)$	<b>04</b>
<b>(c)</b> Explain the following controllers (!) PID controller (2) P controller (3) PI controller	<b>07</b>

**OR**

- |   |           |
|---|-----------|
| <b>(a)</b> Define i) State vector ii) Delay time iii) Rise time | <b>03</b> |
| <b>(b)</b> Write properties of transfer function.               | <b>04</b> |
| <b>(c)</b> Find the transfer function of the following fig.     | <b>07</b> |



<b>Q.4 (a)</b> Define i) Marginally stable state ii) Conditional stable state iii) Unstable state.	<b>03</b>
<b>(b)</b> Explain Nyquist Stability Criteria.	<b>04</b>

- (c) Obtain the expression of steady state error. Also, find the equations for static error coefficients. 07

**OR**

- (a) Write advantages of state space approach over classical methods. 03

- (b) Explain polar plot with suitable example. 04

- (c) Write all the rules of Block Diagram Reduction technique. 07

- Q.5** (a) Define i) Gain Margin ii) Frequency response iii) Phase Margin 03

- (b) Explain Mason's Gain Formula. 04

- (c) State and explain compensator. Explain Phase-Lag compensator in detail. 07

**OR**

- (a) Compare open loop and closed loop control systems. 03

- (b) Explain gain crossover frequency and phase crossover frequency. 04

- (c) Explain Phase-Lead compensator in detail. 07

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