Seat No.: Enrolment No

GUJARAT TECHNOLOGICAL UNIVERSITY

BE - SEMESTER-VII (NEW) EXAMINATION – SUMMER 2022

Subject Code:3170203 Date:14/0			5/2022	
Sul	oject	Name: Vehicle Dynamics		
Time:02:30 PM TO 05:00 PM Total Marks: Instructions:				
		Make suitable assumptions wherever necessary.		
		Figures to the right indicate full marks.		
	4.	Simple and non-programmable scientific calculators are allowed.	MARKS	
Q.1	(a)	Define: (i) Rolling Moment (ii) Yawing Moment (iii) Heading Engle	03	
	(b)	Explain air pressure distribution over the vehicle body in brief.	04	
	(c)	Derive the expression of vehicle dynamic axle loading condition and	07	
		conclude that if vehicle is parked on level ground, height of CG does not		
		affect axle loading condition.		
0.4	(a)	Duryy and symbols couth's fixed coordinate system yeard in vahiola dymamic	02	
Q.2	(a)	Draw and explain earth's fixed coordinate system used in vehicle dynamic system.	03	
	(b)	Enlist any four aerodynamic aids and explain rear spoiler in brief with neat	04	
	(6)	sketch.	04	
	(c)	Calculate the max tractive effort and max corresponding road speed with	07	
	(0)	following data:	0.	
		Tractive effort= 201 ft.lb		
		Transmission ratio & efficiency = $4.28 \& 0.966$		
		Final drive ratio & efficiency = 2.92 & 0.99		
		Wheel radius = 12 in/ft		
		Engine speed = 4400 rpm		
		Wheel rotation = 36.87 rad/sec		
		OR		
	(c)	Define drag force and explain aerodynamic pressure drag around various	07	
		shaped bodies.	0.2	
Q.3	(a)	Differentiate between dependent and independent suspension system with	03	
	(b)	example.	0.4	
	(b)	Explain the tyre axis system in brief with neat sketch.	04 07	
	(c)	Explain the effect of slip angle and tyre type on vehicle cornering performance.	07	
		OR		
Q.3	(a)	Explain the Mac person strut type suspension in short.	03	
~	(b)	Explain the effect of conicity of tyre on vehicle performance.	04	
	(c)	Explain the effect of tyre tread design and tyre inflation pressure on vehicle	07	
	. ,	cornering performance.		
Q.4	(a)	Define: Roll center, Roll axis and Roll center height	03	
	(b)	Explain active suspension system in brief for vehicle.	04	
	(c)	Deliver the expression for anti-squat drive mechanism for vehicle equipped	07	
		with trailing arm with neat sketch.		
_		OR		
Q.4	(a)	Define: Caster angle, Toe angle and Camber angle	03	
	(b)	Explain steering linkages in brief and give condition of correct Ackerman	04	
	(.)	steering geometry.	Λ=	
	(c)	Explain the Anti-dive suspension geometry with neat sketch.	07	

Q.5	(a)	Explain under steer, over steer and natural steer.	03
	(b)	Explain four wheel steering system in brief.	04
	(c)	Explain quasi static rollover of rigid vehicle showing all acting forces.	07
		OR	
Q.5	(a)	Explain working of anti-roll bar and its importance in automobile.	03
	(b)	Define fork offset and wheel flop of motorcycle.	04
	(c)	Explain steering geometry errors in details.	07
