

**GUJARAT TECHNOLOGICAL UNIVERSITY****BE - SEMESTER-VI (NEW) EXAMINATION – SUMMER 2024****Subject Code:3160919****Date:24-05-2024****Subject Name:Electric Drives****Time:10:30 AM TO 01:00 PM****Total Marks:70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Simple and non-programmable scientific calculators are allowed.

		MARKS
<b>Q.1</b>	(a) Define electric drive and give the classification of electric drive.	<b>03</b>
	(b) Why current sensing is required in electrical drives? Enlist common methods of current sensing.	<b>04</b>
	(c) Explain the multi quadrant operation of electrical drives with suitable conventions and example.	<b>07</b>
<b>Q.2</b>	(a) Briefly explain the steady state analysis of electrical drive.	<b>03</b>
	(b) Explain principle of operation of chopper.	<b>04</b>
	(c) A 5 KW, 220 V shunt motor has an armature resistance of $0.5 \Omega$ and a field resistance of $220 \Omega$ . At no load motor runs at 1000 rpm and draws a current of 5 A. At full load and rated voltage, the current drawn is 15 A and armature reaction caused a drop of 2 % in flux. Calculate: (1) Full load speed (2) Full load torque.	<b>07</b>
	<b>OR</b>	
	(c) A 200 V dc series motor resistance is $0.5 \Omega$ . motor runs at 800 rpm when operating at its full load current of 10 A and magnetic circuit can be assumed unsaturated. what will be the speed if (1) load torque is increased by 50 % (2) Motor current is 5 A.	<b>07</b>
<b>Q.3</b>	(a) Enlist method employed for speed control of DC series motor.	<b>03</b>
	(b) State & explain the important features of various braking methods of dc motors.	<b>04</b>
	(c) Explain the dynamic model of dc drive in detail.	<b>07</b>
	<b>OR</b>	
<b>Q.3</b>	(a) Enlist method employed for speed control of DC shunt motor.	<b>03</b>
	(b) Explain position control of DC motor.	<b>04</b>
	(c) Derive the expression for average motor current, RMS motor current, torque and average motor voltage for chopper fed d.c. series motor.	<b>07</b>
<b>Q.4</b>	(a) Write down advantages of v/f control other scalar control techniques.	<b>03</b>
	(b) Explain different effect of harmonics on induction motor drive.	<b>04</b>
	(c) Explain constant air gap flux control scheme for induction motor drives.	<b>07</b>
	<b>OR</b>	
<b>Q.4</b>	(a) Compare VSI fed Induction motor drive with CSI fed induction motor drive.	<b>03</b>

- (b) For Variable frequency control of induction motor explain the following point **04**
1. For speed below base speed, why (v/f) ratio is maintained constant?
  - For speed above base speed, why terminal voltage is maintained constant?
- (c) Explain closed loop speed control of induction motor using slip control scheme. **07**
- Q.5** (a) Write down advantages of squirrel-cage induction motor over dc motors. **03**
- (b) State & explain briefly different methods of speed sensing. **04**
- (c) Explain how static rotor resistance control is achieved during starting of induction motor. **07**

**OR**

- Q.5** (a) Discriminate the constant torque and constant power region from torque speed characteristics of 3 phase induction motor. **03**
- (b) Explain space vector modulation technique. **04**
- (c) Explain any one slip power recovery scheme for slip ring induction motor. **07**

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