

**GUJARAT TECHNOLOGICAL UNIVERSITY****BE – SEMESTER- VII EXAMINATION-SUMMER 2023****Subject Code: 3170915****Date: 30/06/2023****Subject Name: Power System Dynamics and Control****Time: 10:30 AM TO 01:00 PM****Total Marks: 70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Simple and non-programmable scientific calculators are allowed.

		<b>MARKS</b>
<b>Q.1</b>	(a) Define power system stabilizer.	<b>03</b>
	(b) Explain in the types of load models used in power system	<b>04</b>
	(c) Mention the transformation matrix used and corresponding assumptions for Park's transformation. Describe the significance of Park's transformation.	<b>07</b>
<b>Q.2</b>	(a) Draw the systematic diagram for 3-phase synchronous machine.	<b>03</b>
	(b) Explain three- Damper wiring model with figure.	<b>04</b>
	(c) Give a classification of load models used in power system analysis. Briefly explain any one load model in detail.	<b>07</b>
	<b>OR</b>	
	(c) Draw general functional block diagram of an excitation control system and explain the function of each block.	<b>07</b>
<b>Q.3</b>	(a) What is meant by speed governing system?	<b>03</b>
	(b) State basic assumptions made in steady state analysis of an alternator	<b>04</b>
	(c) Briefly describe the phenomenon of Sub-Synchronous Resonance. Describe any two techniques for SSR mitigation.	<b>07</b>
	<b>OR</b>	
<b>Q.3</b>	(a) Briefly explain the procedure of small signal analysis	<b>03</b>
	(b) Define the Classification of stability and Explain any one in details.	<b>04</b>
	(c) What is voltage stability? Explain with neat diagrams.	<b>07</b>
<b>Q.4</b>	(a) Explain classification of Bracking.	<b>03</b>
	(b) Using Part transformation derive voltage equation of synchronous machine.	<b>04</b>
	(c) Explain transmission line modeling by D-Q transformation using $\alpha$ - $\beta$ variables.	<b>07</b>
	<b>OR</b>	
<b>Q.4</b>	(a) Explain excitation system.	<b>03</b>
	(b) Explain three- Damper wiring model with figure.	<b>04</b>
	(c) Briefly explain : Discrete Control of HVDC Links.	<b>07</b>
<b>Q.5</b>	(a) Explain application of Model 1.1.	<b>03</b>
	(b) Why load is consider as a constant impedance model?	<b>04</b>
	(c) Compare voltage and angle stability. How to carry out integrated analysis of the same.	<b>07</b>
	<b>OR</b>	
<b>Q.5</b>	(a) Explain classification of Bracking.	<b>03</b>
	(b) Explain any one method for analysis of voltage instability.	<b>04</b>

(c) Briefly explain: Dynamic Braking.

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