## **GUJARAT TECHNOLOGICAL UNIVERSITY**

**BE- SEMESTER-V (NEW) EXAMINATION – WINTER 2024** 

Subject Code:3150504 Date:17-12-2024

**Subject Name:Instrumentation and Process Control** 

Time:10:30 AM TO 01:00 PM Total Marks:70

## **Instructions:**

- 1. Attempt all questions.
- 2. Make suitable assumptions wherever necessary.
- 3. Figures to the right indicate full marks.
- 4. Simple and non-programmable scientific calculators are allowed.

			Marks
Q.1	(a)	Give the Laplace transform for the following  1. Cos kt  2. Sinh kt  3. $e^{-at}$	03
	<b>(b)</b>	State and prove the final value theorem.	04
	(c)	Solve the following by using Laplace transforms $\frac{dx}{dt} + x = 1 \qquad x(0) = 0$	07
Q.2	(a)	Define the following  1. Gain  2. Transportation Lag  3. Time Constant	03
	<b>(b)</b>	List the assumption made for derivation of transfer function of mercury thermometer and justify.	04
	(c)	Derive the transfer function and step response of mixing process. <b>OR</b>	07
	(c)	A Storage tank contains a liquid which is pumped by a centrifugal pump at as steady rate. Liquid enters the tank at volumetric flow rate 200 Liter/hr and liquid level reaches steady-state value of 40 cm. If input flow rate is suddenly increased to 300 Liter/hr, Find level response and liquid level after 1 minutes by deriving transfer function and step response. (Cross section area of tank: 15 cm x 15 cm)	07
Q.3	(a)	What are advantages and disadvantages of P-control? Give application of P-Control.	03
	<b>(b)</b>	Discuss characteristics of underdamped step response for second order system.	04
	(c)	Derive the transfer function of U tube manometer as second order system.	07
		OR	
Q.3	(a)	Explain the following in control system  1. Load Variable  2. Set Point  3. Control Variable	03

	<b>(b)</b>	Differentiate between Feed-forward control and Feed-back control.	04
	(c)	Derive the transfer function of two non-interacting tanks and discuss nature of response after compare with second order system.	07
Q.4	(a)	What is controller? Explain its importance in close loop control system.	03
	<b>(b)</b>	What are advantages and disadvantages of PI-control? Give application of PI-Control.	04
	(c)	The characteristics equation of control system is given as following $s^3 + 3s^2 + 2s + K = 0$	07
		Determine  (1) The value of K for which system is stable system using Routh test  (2) The value of K for which system is marginally stable  (3) The frequency of system for sustain oscillations	
		OR	
Q.4	(a)	Explain the working of cascade control system.	03
	<b>(b)</b>	Differentiate between servo-type and regulator-type problem.	04
	(c)	Explain the frequency response analysis of First order control system by bode diagram.	07
Q.5	(a)	Discuss the advantages with application of DCS.	03
	<b>(b)</b>	Explain the working principal and construction of Thermocouples.	04
	(c)	Explain principle, construction and working of bubbler system.  OR	07
Q.5	(a)	List the static and dynamic characteristics of Instruments.	03
	<b>(b)</b>	List the various instrument used for Viscosity measurement and explain working of any one.	04
	(c)	Explain principle, construction and working of pirani vacuum gauge.	07

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