

GUJARAT TECHNOLOGICAL UNIVERSITY**BE - SEMESTER-V(NEW) EXAMINATION – SUMMER 2022****Subject Code:3150504****Date:07/06/2022****Subject Name:Instrumentation and Process Control****Time:02:30 PM TO 05:00 PM****Total Marks: 70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Simple and non-programmable scientific calculators are allowed.

MARKS

- Q.1**
- | | | |
|-----|--|-----------|
| (a) | Define step and input function. | 03 |
| (b) | Find the Laplace transform of $f(t) = 1$ & $f(t) = t$ | 04 |
| (c) | Derive the transfer function of mercury thermometer. Determine the response equation of mercury thermometer for step function. | 07 |

- Q.2**
- | | | |
|-----|---|-----------|
| (a) | Solve $\frac{dx}{dt} + 3x = 0, x(0) = 2$ | 03 |
| (b) | Derive the transfer function for Interacting system. | 04 |
| (c) | Solve the following differential equation by Laplace transform: | 07 |

$$\frac{d^3x}{dt^3} + 2\frac{d^2x}{dt^2} - \frac{dx}{dt} - 2x = 4 + e^{2t}$$

$$x(0) = 1, x'(0) = 0, x'' = -1$$

OR

- (c) Find the inverse Laplace Transform of the function:
- $$\bar{x}(s) = \frac{4s + 5}{(s-1)^2(s+2)}$$
- 07**

- Q.3**
- | | | |
|-----|--|-----------|
| (a) | Define dead zone and dead time lag | 03 |
| (b) | Explain Servomechanism type problem and Regulator problem | 04 |
| (c) | Define second order system. Derive the transfer function of U-Tube Manometer | 07 |

OR

- Q.3**
- | | | |
|-----|---|-----------|
| (a) | Derive transfer function for transportation lag. | 03 |
| (b) | Define: overshoot, decay ratio, response time and period of oscillations. | 04 |
| (c) | Write a note on Bellows differential pressure element with neat sketch. | 07 |

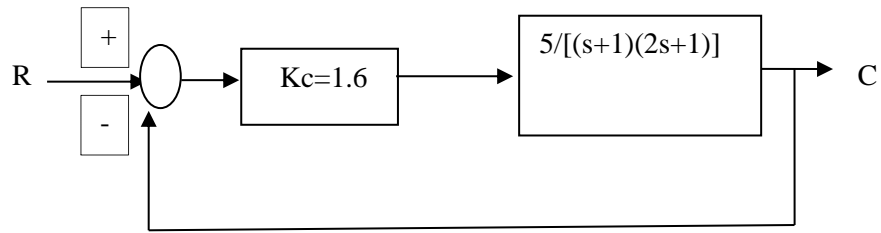
- Q.4**
- | | | |
|-----|--|-----------|
| (a) | Distinguish between Negative Feedback and Positive Feedback. | 03 |
| (b) | Describe the importance of root locus method in brief. | 04 |
| (c) | Discuss pressure spring thermometer with neat sketch. | 07 |

OR

- Q.4**
- | | | |
|-----|---|-----------|
| (a) | Highlight on hygrometer & hydrometer. | 03 |
| (b) | Differentiate between Open loop and closed loop control system. | 04 |
| (c) | Given the characteristic equation, determine the stability by the Routh criterion | 07 |
- $$s^4 + 3s^2 + 5s^2 + 4s + 2 = 0$$

- Q.5**
- | | | |
|-----|--|-----------|
| (a) | Describe PLC, DCS, and SCADA in brief. | 03 |
| (b) | Describe the bubbler system for liquid level measurement with neat sketch. | 04 |

- (c) The set point of the control system shown in figure below is given a step change of 0.1 unit. Determine: (a) The maximum value of C and (b) The offset. **07**



OR

- Q.5** (a) Write significance of gain margin and phase margin. **03**
(b) What is offset? Explain P, PI and PID controller. **04**
(c) Plot the bode diagram for the system whose overall transfer function is $1/(s+1)(s+5)$ **07**
