

GUJARAT TECHNOLOGICAL UNIVERSITY**BE - SEMESTER-VII (NEW) EXAMINATION – WINTER 2023****Subject Code:3171003****Date:04-12-2023****Subject Name: Digital Signal Processing****Time: 10:30 AM TO 01:00 PM****Total Marks:70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Simple and non-programmable scientific calculators are allowed.

- Q.1** (a) Define the following systems: Accumulator, forward difference, backward difference. **03**
- (b) Explain commutative, distributive and associative properties of linear convolution. **04**
- (c) Discuss the inverse system and explain how a system and its inverse system both can be causal and stable. **07**
- Q.2** (a) Give one example for each system: Memoryless, Time-invariant, stable. **03**
- (b) Relate Z.T with DTFT. Also give applications of Z.T. **04**
- (c) Explain differentiation and convolution properties of DTFT. **07**
- OR**
- (c) Explain differentiation and convolution properties of ZT. **07**
- Q.3** (a) A system function is given by $H(z) = \frac{1}{(1-0.25z^{-1})}$, then find corresponding difference equation and impulse response. **03**
- (b) If $H(z) = 1 + \frac{1}{2}z^{-1} + \frac{1}{2}z^{-2} + z^{-3}$, then realize this function with minimum number of multipliers. **04**
- (c) Find magnitude and phase response at $\omega=0$ and π for a system function $H(z) = \frac{1}{(1-0.5z^{-1})}$ **07**
- OR**
- Q.3** (a) Discuss All pass system briefly. **03**
- (b) Explain structures for linear phase FIR systems. **04**
- (c) Find out all pass and minimum phase description of given system $H(z) = \frac{(1+3z^{-1})}{(1+0.5z^{-1})}$ **07**
- Q.4** (a) Give advantages of digital filters. **03**
- (b) Discuss design steps of IIR filter using bilinear transformation. **04**
- (c) Explain basic structure for IIR systems. **07**
- OR**
- Q.4** (a) Give limitations of Impulse Invariance method of designing IIR filter. **03**
- (b) Discuss Goertzel algorithm. **04**
- (c) Explain design of FIR filters by Kaiser window and mention its advantages against the commonly used windows. **07**
- Q.5** (a) Define N-point DFT & IDFT. What is Twiddle factor ? **03**
- (b) Discuss types of linear phase FIR systems. **04**

(c) Explain decimation in frequency algorithm for radix-2. **07**

OR

Q.5 (a) Briefly explain frequency warping and pre-warping. **03**

(b) Convert the given Analog Filter in to the digital filter using impulse invariance technique. **04**

$$H_a(s) = (s + a) / \{(s + a)^2 + b^2\}$$

(c) If a causal sequence is given by $x(n) = \cos(n\pi/2)$, $0 \leq n \leq 3$, **07**
 $= 0$, otherwise. ,

then compute 4 point DFT.
